

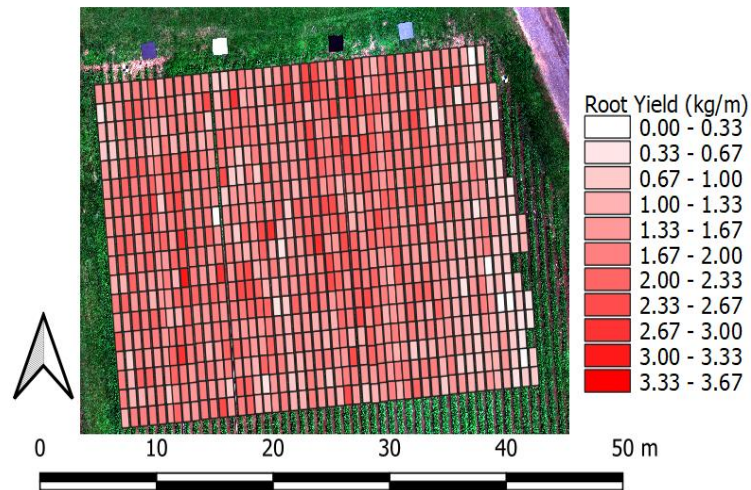
# Assessing Multi-season Table Beet Root Yield from Unmanned Aerial System



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# Background

- Sustainable agricultural practice calls for accurate harvest yield estimation to optimize logistics, reduce waste, and improve resource use.
- UAS provides high throughput, spatially-explicit information about a field, enabling precise and timely interventions for improved crop management.



- Challenges in existing UAS yield prediction:
  - Subterranean crop yield prediction is under-researched, e.g., beets, carrots, potato, etc.
  - Existing models are growth stage, harvest time, and season-dependent, thus limiting scalability and flexibility.



# Objectives

- Develop a methodology for a robust beet root yield model
- Assess the scalability of the model across:
  - Growing seasons
  - Data collection times within-season
  - Variable harvest timing



# Data collection

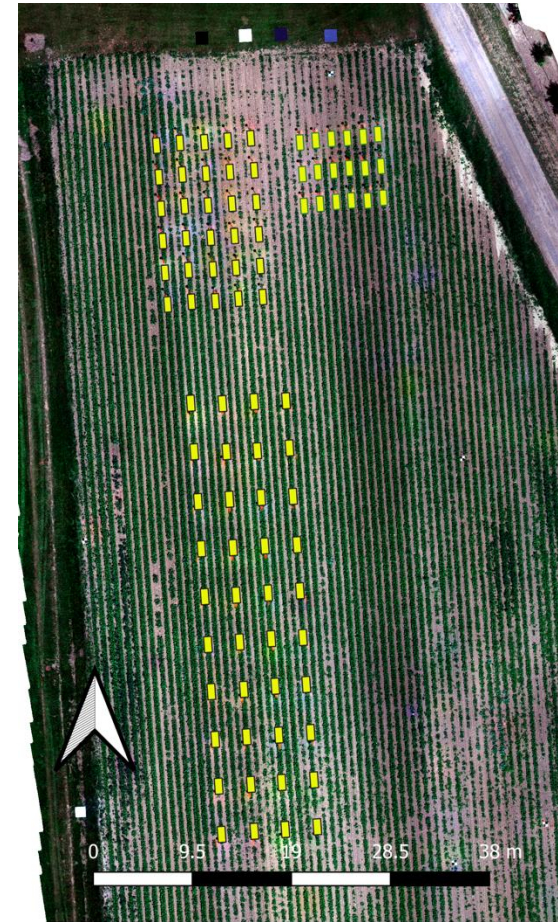
- Conducted flights with DJI Matrice 600 over Cornell Agritech field in Geneva, NY, during 2021 and 2022 season.
- Images captured using Micasense Red Edge -M
- Dimensions for the plots are 5ft x 1 ft
- Table beetroot weight measured at harvest only.



MicaSense  
Rededge-M  
(blue, green, red,  
red-edge, and near  
infrared bands)

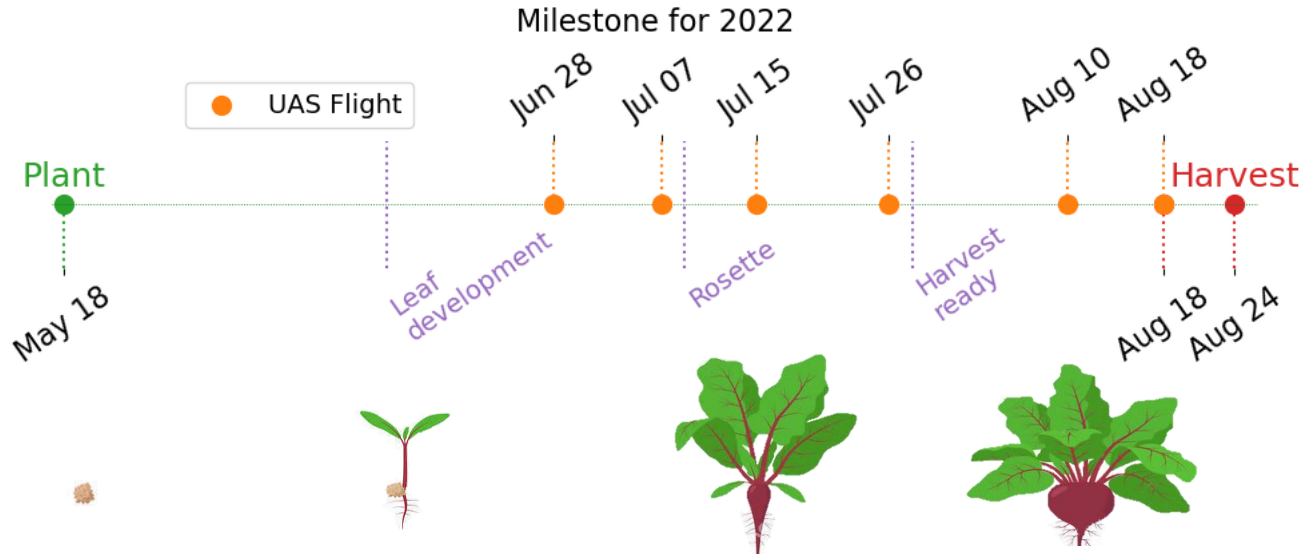


*Field view of the beet plots under study*



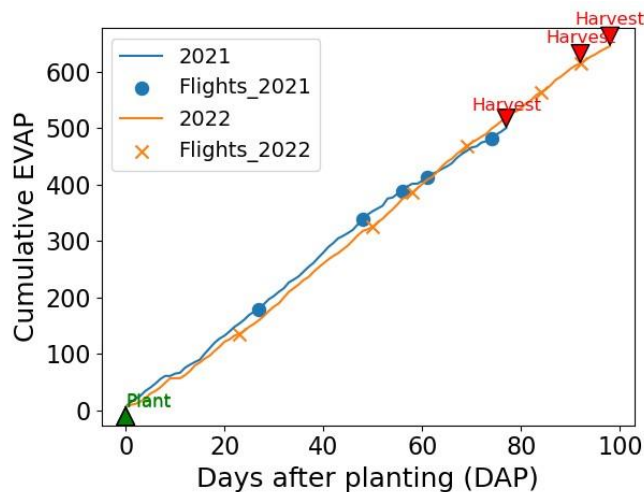
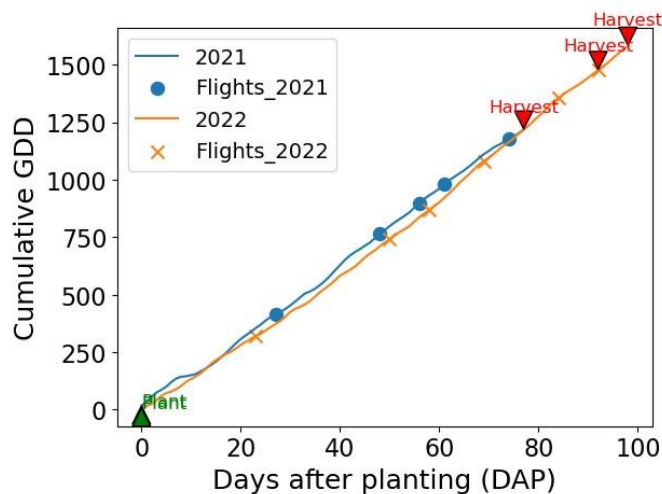
*Ortho-mosaic of the entire beet plot. The yellow rectangles are the plots under study.*

# Timeline



# Meteorology

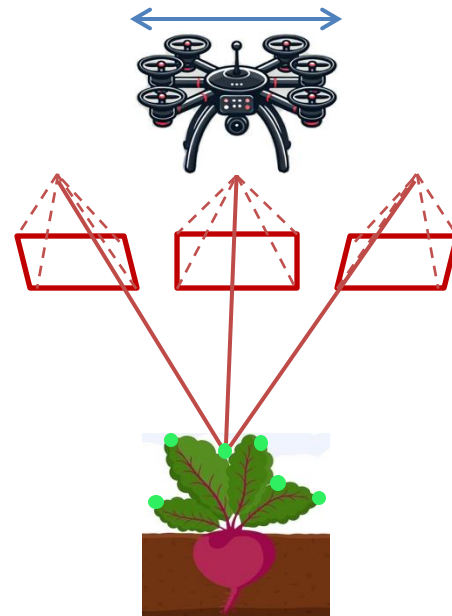
- Growing degree days (GDD) is widely used strategy to track growth stages in crops.
  - $$GDD = \frac{T_{max} + T_{min}}{2} - T_{base}$$
- Evapotranspiration has been shown to be directly proportional to yield.
  - Accumulated pan evaporation data was used as model feature.



# Structure



- Pix4D was used to generate point clouds through structure-from-motion.
- Generated digital surface model (DSM) and digital terrain model (DTM).
- Evaluated canopy height model (CHM)
  - $CHM = DSM - DTM$
- Canopy volume estimated by summing the heights of the extracted vegetation.



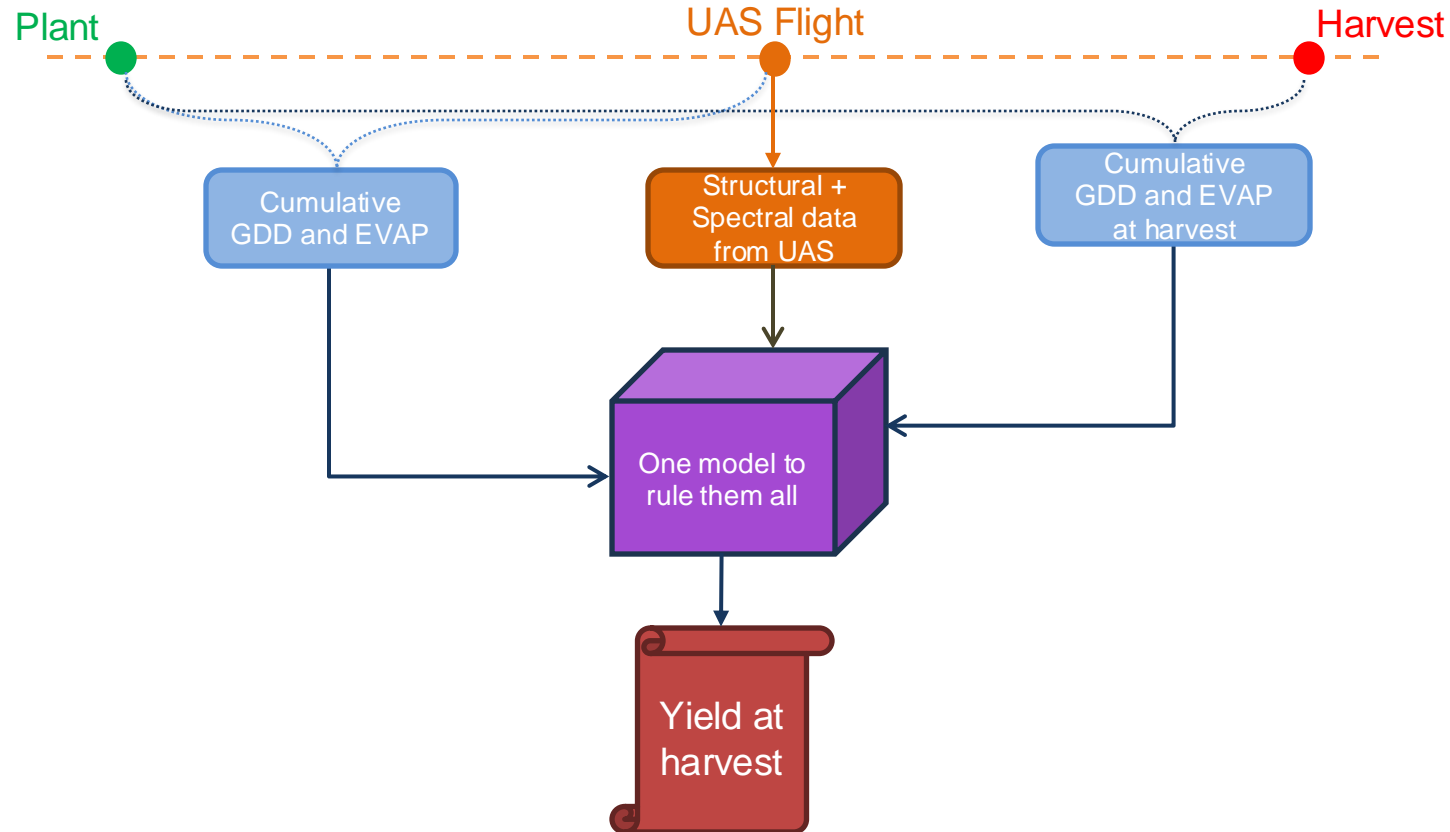
# Spectral features

- Extracted mean canopy spectra.
- Obtained vegetation indices.
- Correlation, mutual information-based feature selection was applied to extract relevant uncorrelated features.
  - Features with a mutual information score above 75<sup>th</sup> percentile to harvest root yield and an inter-correlation below 0.8.

Name	Formula
Green normalized difference vegetation index (GNDVI)	$\frac{R_{800} - R_{570}}{R_{800} + R_{570}}$
Transformed chlorophyll absorption ratio index (TCARI)	$3 \times [(R_{700} - R_{670}) - 0.2 \times (R_{700} - R_{550})(R_{700}/R_{670})]$
Mean green reflectance	$R_{550}$

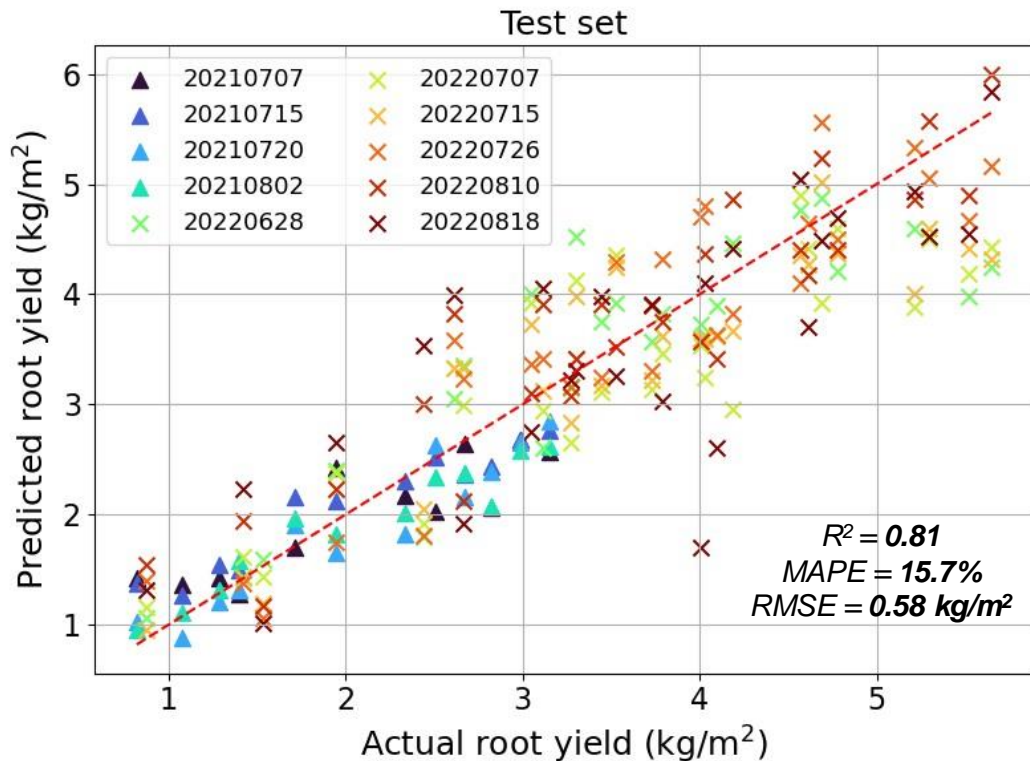


# Yield modeling

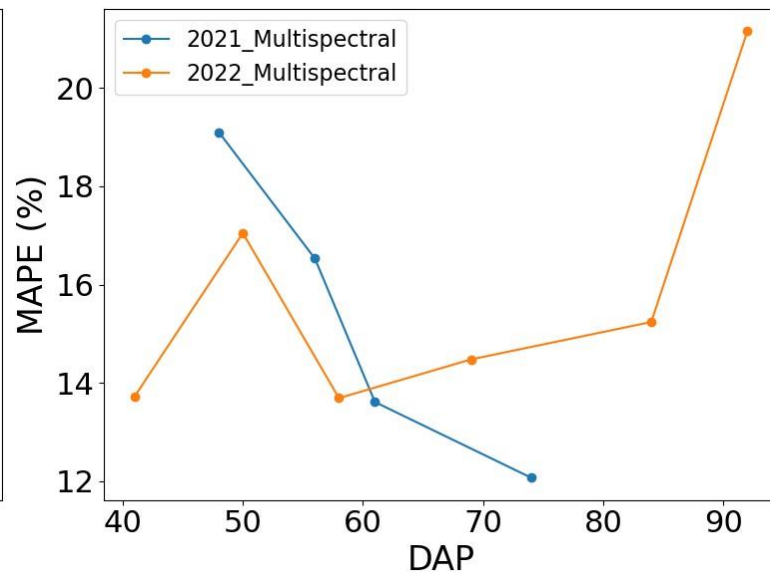
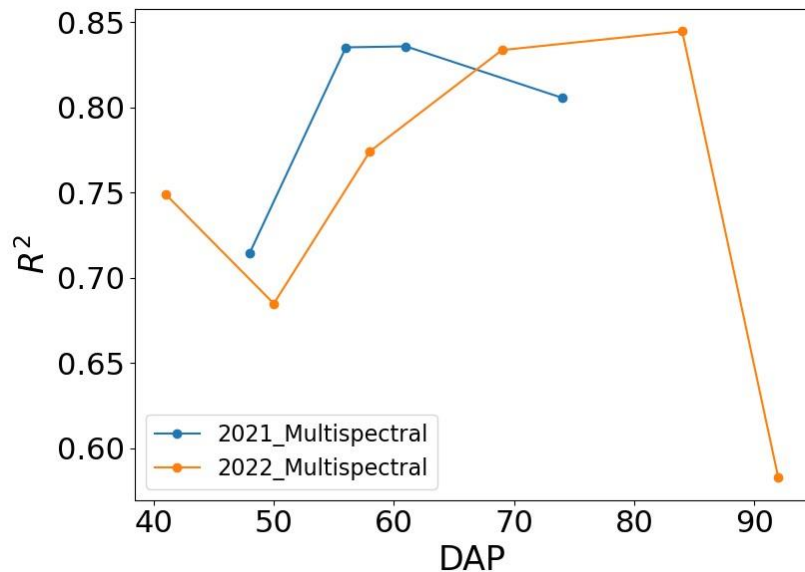


# Model performance

Model trained on 70% of 2022 data and 30% of 2021 data



# Performance breakdown by flight



- Peak model performance between 55~85 days (late rosette to harvest-ready stage)
- Relatively poor performance for the final 2022 flight was attributed to defoliation and weed growth

# Conclusions

- Estimated harvest table beet root yield across two seasons using UAS multispectral data at overall  $R^2 = 0.81$  and  $MAPE = 15.7\%$ .
- The end of the rosette stage and early harvest-ready stage proved to be ideal for optimal model performance.
- While our model has demonstrated reliability within the growth stages and harvest times reported, developing a truly robust and scalable model requires additional datasets spanning diverse growth stages and harvest timing.



# Questions?



For further queries feel free to contact me at **ms4667@rit.edu**

LinkedIn



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