Predicting Table Beet Root Yield via UAS-based Hyperspectral Imagery





Objectives

We proposed to develop UAS-based techniques to forecast beet root weight. This includes:

- Identifying the spectral regions that are predictive of beet root weight.
- Evaluating the predictability at five different growth stages.
- Assessing the extension of results to affordable, operational silicon-based detectors. Note: We used hyperspectral imagery to determine the optimal wavelengths in the Si-range (400-900 nm).

Data collection process



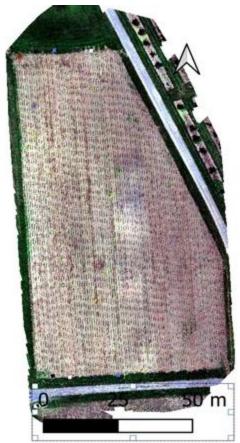


Headwall Nano Hyperspec 400-1000 nm: Visible and

Near Infrared (VNIR) 272 bands; 2-3 nm spectral

resolution









UAS data collection: 2021 flight milestones

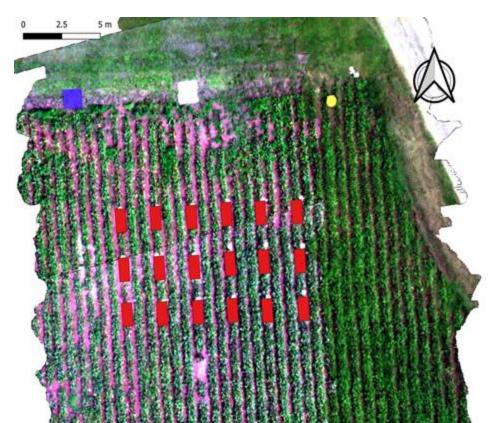


Date	Milestone	Growth Stages
May 20	Beets planted	Germination
June 16	1st Flight	Leaf Development (Crop Emergence)
July 7	2nd Flight	Leaf Development (more than 9 leaves unfolded)
July 15	3rd Flight	Rosette growth
July 20	4th Flight	Rosette growth
August 2	5th Flight	Harvest-ready
August 5	Harvest	Harvest-ready

Plot extraction



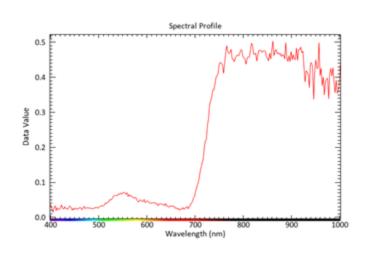
- Convert from radiance to reflectance (via ELM)
- Perform denoising
- 18 plots in our study
- Width of box = 0.67 m (roughly the distance between two adjacent rows)
- Height of box = 1.46 m (roughly the size of the plot)



Challenges related to hyperspectral data



- We have ~272 spectral bands
- Hyperspectral data suffer from the curse of dimensionality
- Identify the useful features:
 - Find all possible pairs of normalised difference indices from mean vegetation spectra of the plot (reflectance features).
 - Find the GLCM mean of a plot (texture features).
 - Find all possible pairs of normalised differences for the GLCM mean

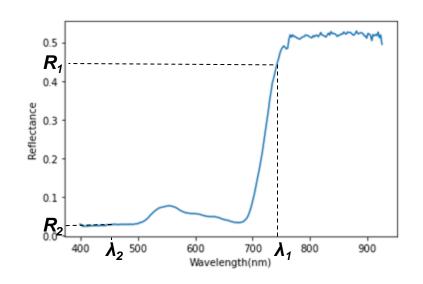


Predictor variable extraction



- Extract normalized difference indices at various wavelength pairs
 - We calculate for both reflectance and texture features
 - For reflectance: Normalized difference reflectance indices (NDRI)
 - For texture: Normalised texture reflectance indices (NDTI)
- Fit a linear relationship between this feature and the value to predict (e.g., root weight)

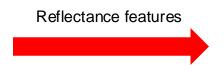
Normalized Difference Indices =
$$\frac{R_1 - R_2}{R_1 + R_2}$$

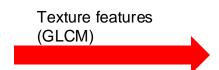


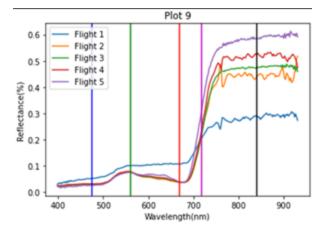
Feature extraction

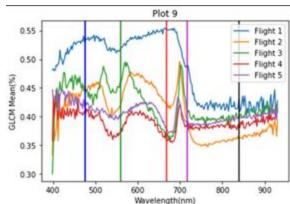








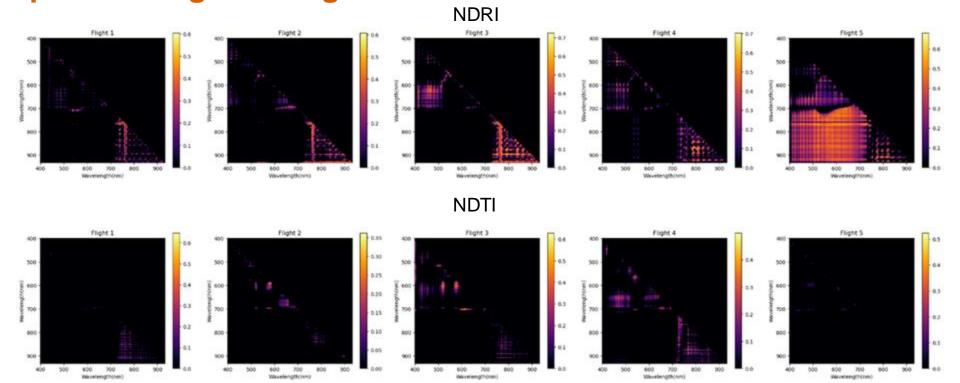




Extract a spectrum of mean reflectectance features and mean texture features from each plot

Plot of coefficient of determination at various wavelength pairs during each flights





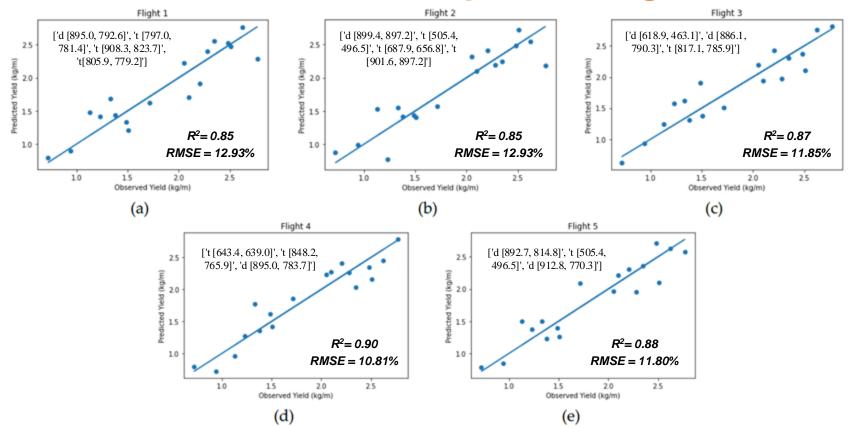
Feature selection for better-performing model



- Select top 10 (R²) from each indices
- Run modified stepwise regression
 - Stepwise regression only accounts for a particular set of features at fixed permutations
 - Here all the top performing feature combinations are reported
 - We randomly select the order of feature
 - First forward select, then perform backward elimination after each selection (to ensure model with a low number of features)
 - Filter out the models containing low VIF (variance inflation factor)

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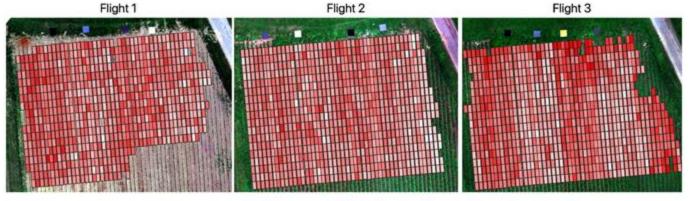
Performance of the best performing models

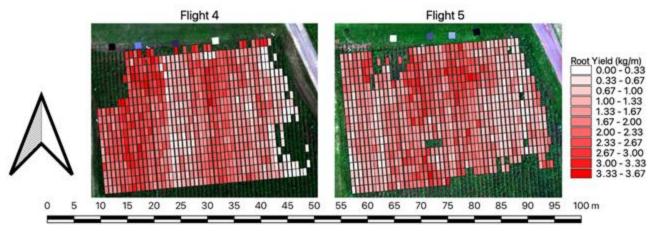




Extrapolating vield results to the field scale







Conclusion and future work



- Feature pairs around the NIR region are most responsive to root yield
- The spectral region of most responsive predictive regions changes with time
- The "rosette" growth stage (flights 3 & 4) are the most suitable time to collect data
- Further verification of the features are required with data sets collected across growing seasons



Questions?

For more details: Forecasting Table Beet Root Yield Using Spectral and Textural Features from Hyperspectral UAS Imagery, Remote Sensing 2023,15

Acknowledgements: Timothy Bauch, Nina Raqueno, Imergen Rosario

Funding: This research principally was supported by Love Beets USA and the New York Farm Viability Institute (NYFVI), as well as the United States Department of Agriculture (USDA), National Institute of Food and Agriculture Health project NYG-625424, managed by Cornell AgriTech at the New York State Agricultural Experiment Station (NYSAES), Cornell University, Geneva, New York.